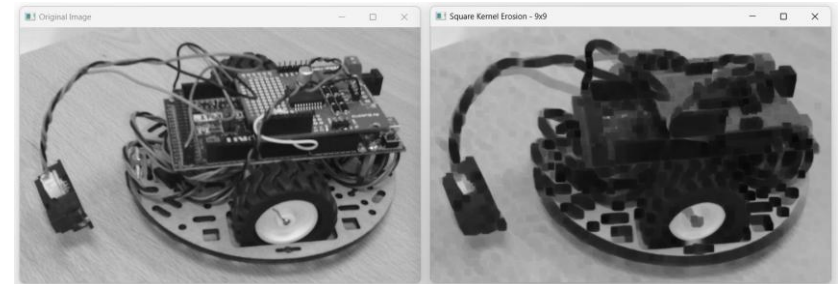
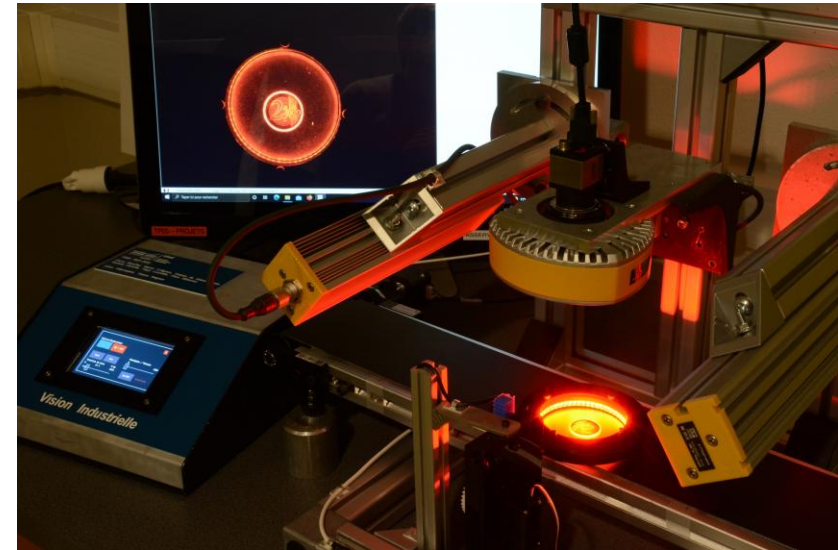
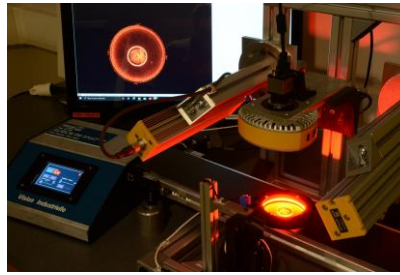


SC 19 – Machine Vision

Image Processing

Julien VILLEMEJANE





SC19 – Image Processing

► At the end of this training, the learners will be able to:

Use basic building blocks of OpenCV

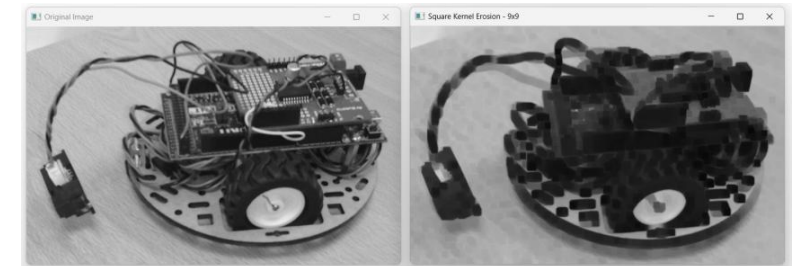
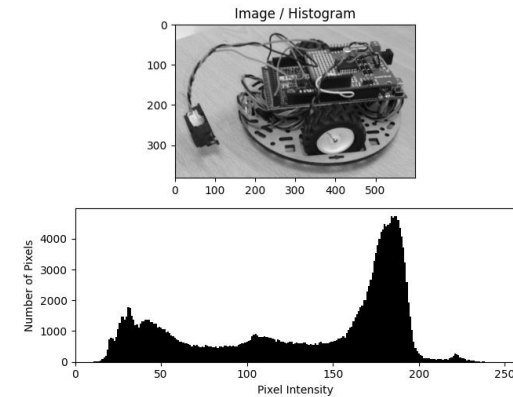
Open an image

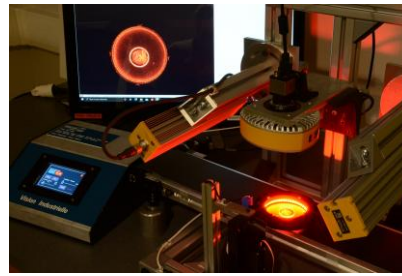
Create the histogram of an image

Apply basic transforms on images

- blur, filters
- erosion, dilation, opening, closing

Display the contour of objects





SC19 – Image Processing

What is image processing for ?

Why is image processing required in a machine vision chain ?

For industrial inspection applications ?

What are the **main processes** ?

What is the goal of each of them ?

What is the ideal **workflow** ?



First Principles of Computer Vision

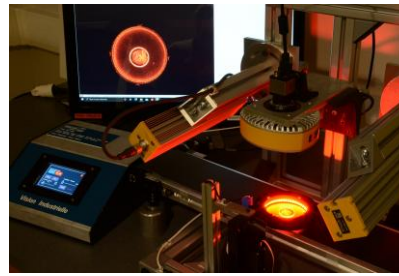
@firstprinciplesofcomputerv3258 · 65,1 k abonnés · 151 vidéos

First Principles of Computer Vision is a lecture series presented by Shree Nayar who is faculty at Columbia University.

fpcv.cs.columbia.edu

Abonné

<https://www.youtube.com/@firstprinciplesofcomputerv3258>



SC19 – Image Processing

Goal of processing an image



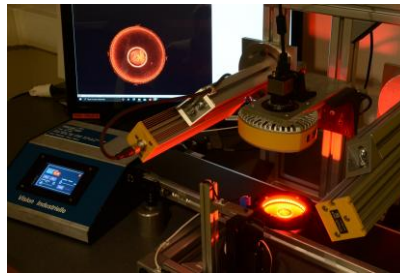
Image from the camera

- **Noise**
- Bad contrast
- Inhomogeneous Lighting
- ...



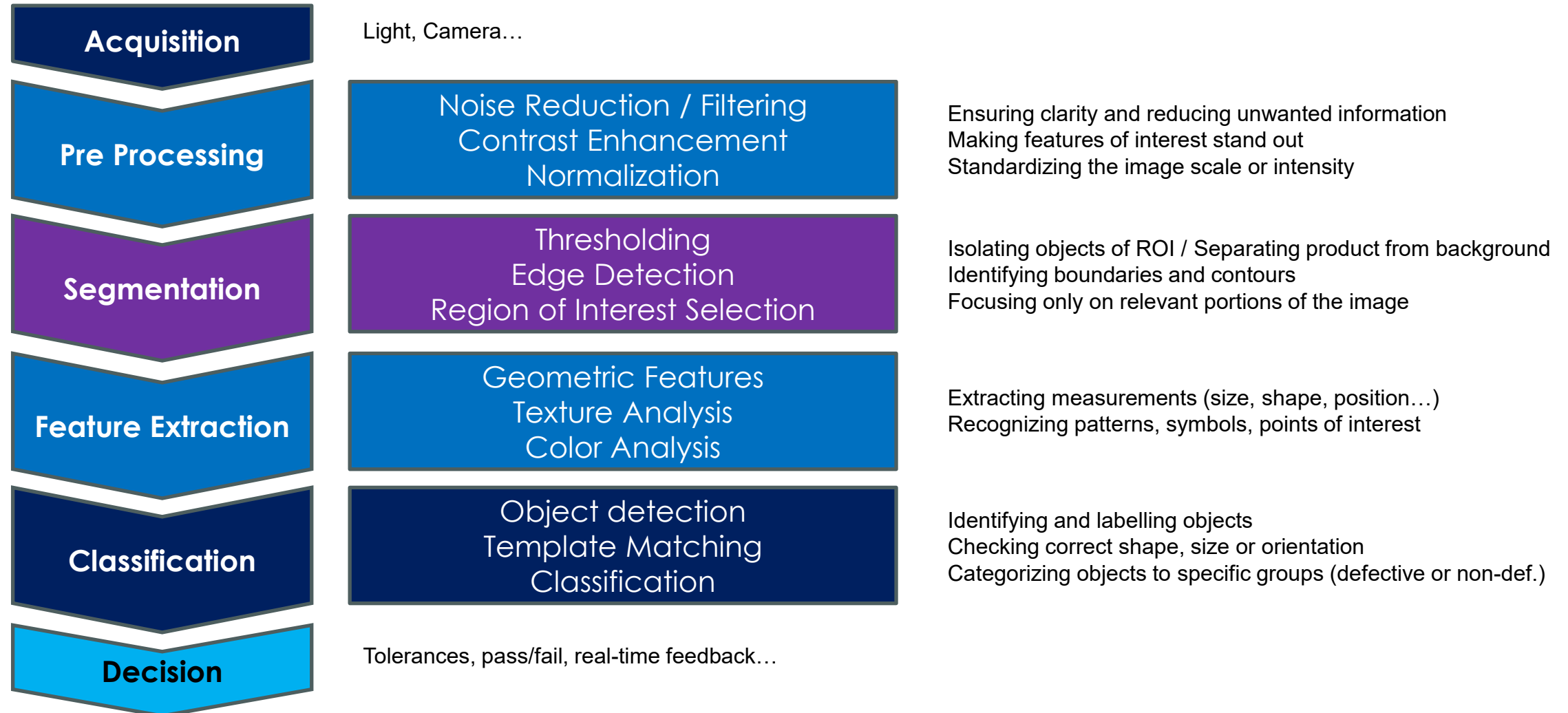
Desired image with objects with
well-defined contours

- Homogeneous zones
- Transition zones



SC19 – Image Processing

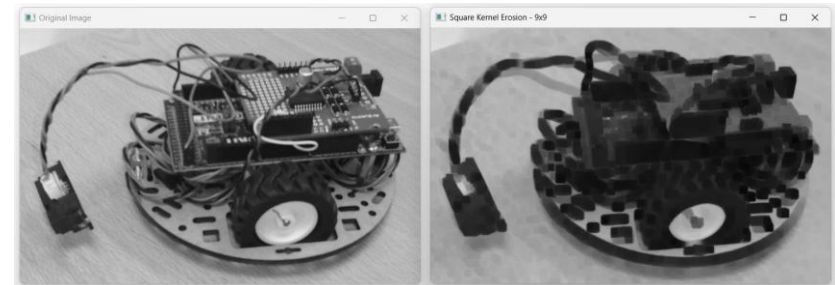
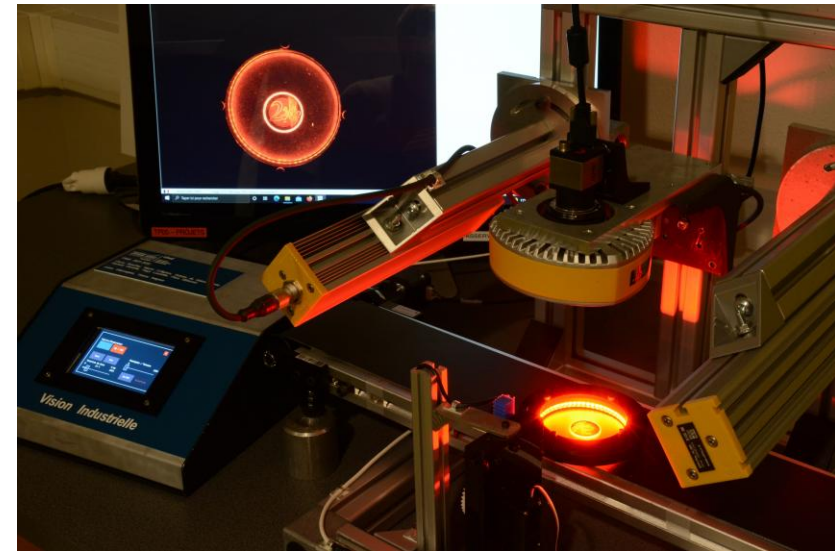
Steps for processing an image

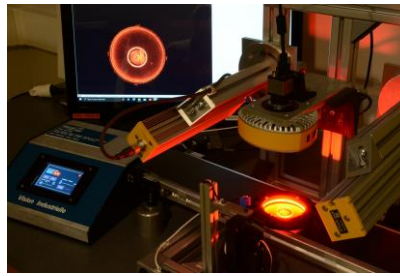


SC 19 – Machine Vision

Image Processing
with OpenCV

Julien VILLEMEJANE





SC19 – Image Processing

What is OpenCV ?

Open Source Computer Vision Library

An open source **computer vision** and machine learning software **library**

supporting multiple programming languages such as Python, C++, Java, and MATLAB

Image Processing

Filtering, Edge detection, Image transformations...

Object Recognition

Detecting objects in images and videos

CV Algorithms

Motion tracking, 3D reconstruction, Augmented reality

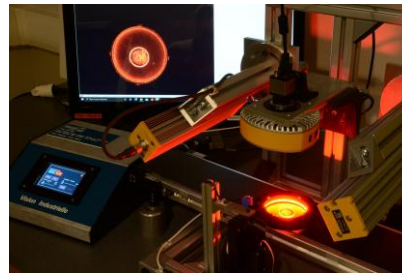
Machine Learning

Image classification, Pattern recognition, Scene Understanding



<https://opencv.org>





SC19 – Image Processing

Installation of OpenCV

Installing OpenCV for Python 3

```
pip install opencv-python
```

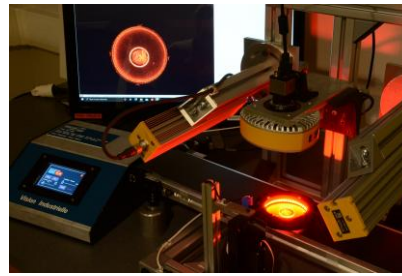
Testing OpenCV importation in a script

```
import cv2  
Cv2.__version__
```



<https://opencv.org>

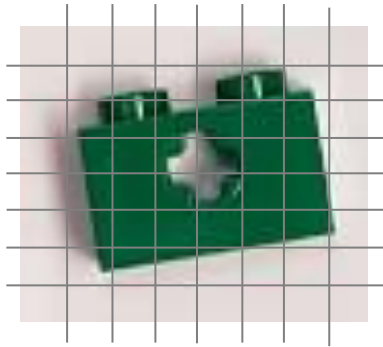




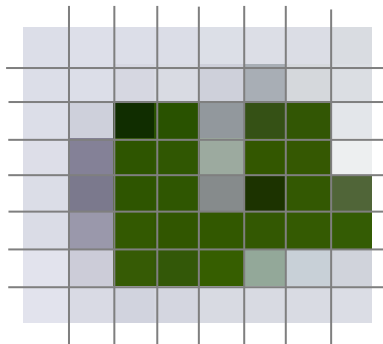
SC19 – Image Processing

Digital Images

Continuous image



Digital image : projection of the continuous image



8 x 8 grid



16 x 16 grid

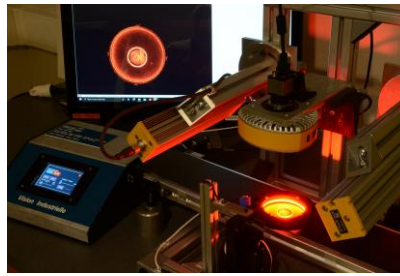


32 x 32 grid

Digital Image

Picture represented in
numerical form

*so that it can be **stored**,
processed, and **displayed** by a
computer or digital device.*

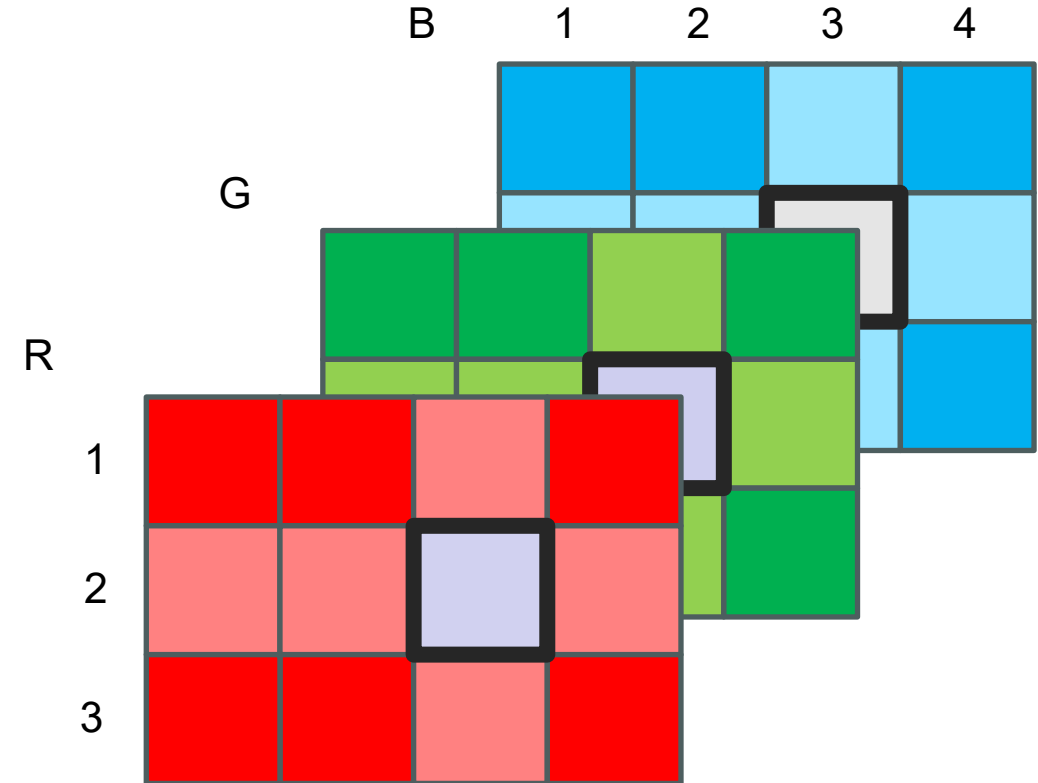
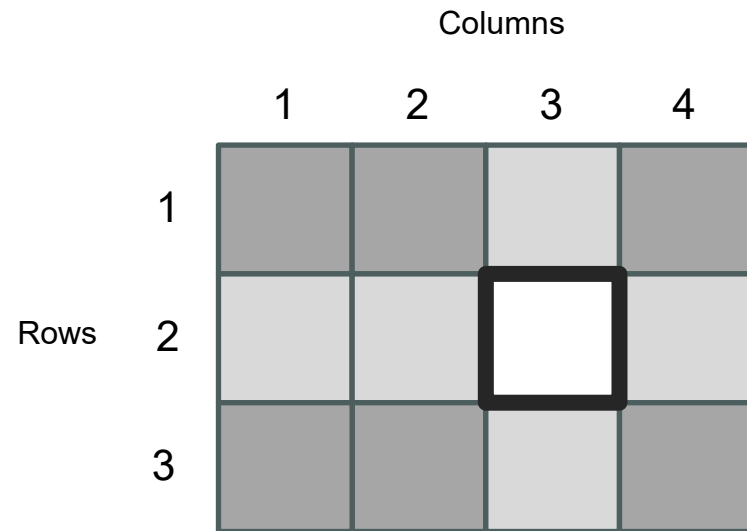


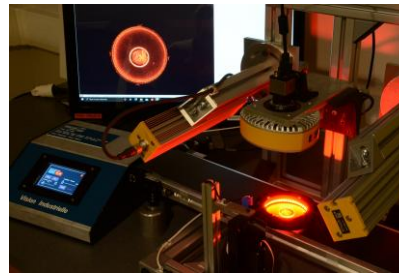
SC19 – Image Processing

Digital Images

GrayScale

Nb of pixels = $h \times v$



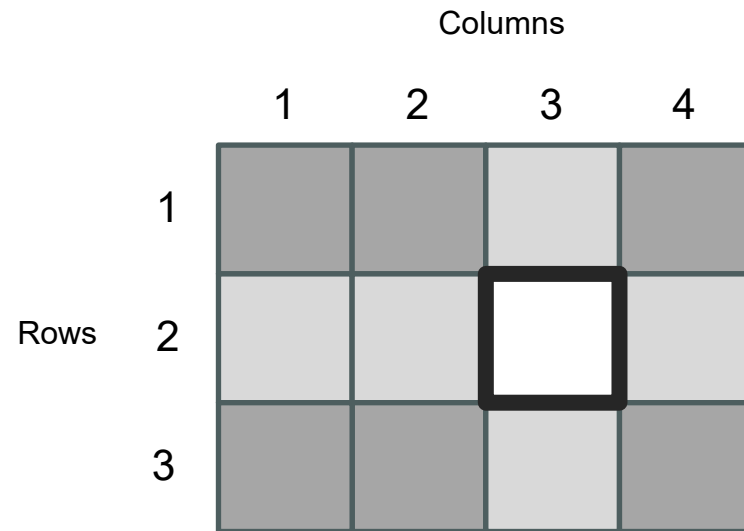


SC19 – Image Processing

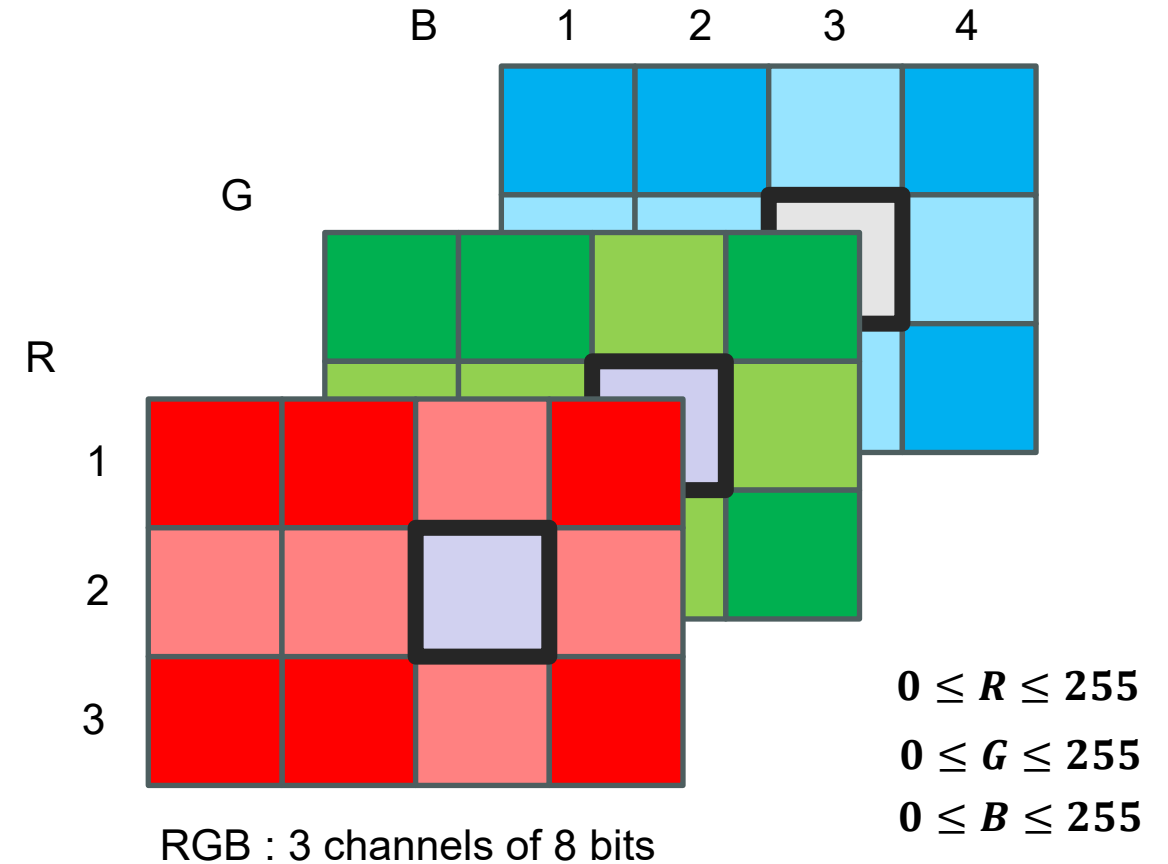
Digital Images / RGB

GrayScale

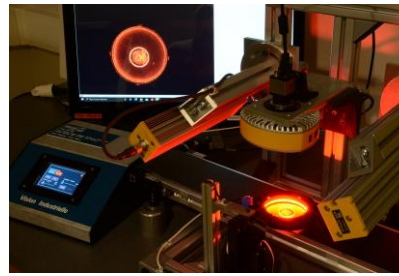
Nb of pixels = $h \times v$



Each pixel is converted into **n bits**.



R=200, G=100, B=50



SC19 – Image Processing

Digital Images / Color spaces

RGB

Used primarily in **electronic displays** like computer screens, cameras, and scanners. The combination of these three primary colors at various intensities can produce any color.

HSV

Used in **image editing**. It separates image's color from its brightness.

Hue : type of color

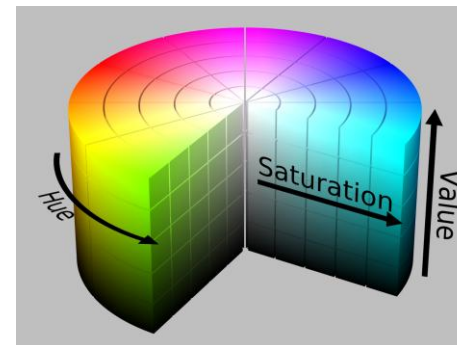
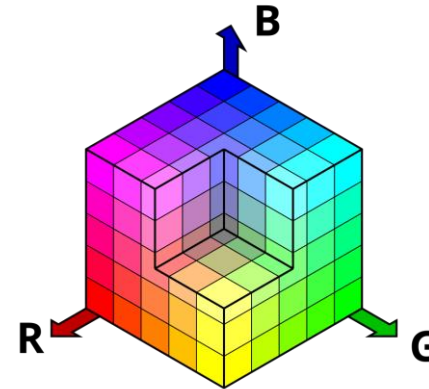
Saturation : intensity of the color

Value : Brightness of the color

CMYK

LAB

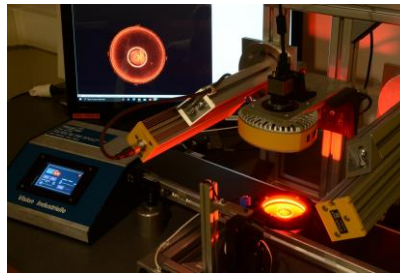
YUV



Color Space

Model for **representing colors** in a consistent and reproducible way

Each color space uses a different method for organizing and describing color, depending on the purpose or application



SC19 – Image Processing

Digital Images / Color spaces

Color Space

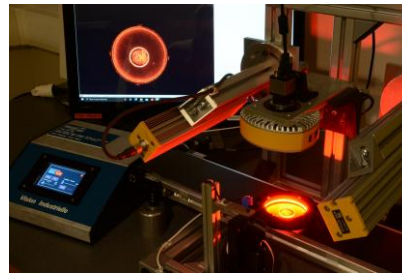
Table 9 from

Segmentation of Images by Color Features: A Survey - Scientific Figure on ResearchGate.

Available from: https://www.researchgate.net/figure/Advantages-and-disadvantages-of-color-spaces_tbl7_323632019 [accessed 10 Oct 2024]

Model for **representing colors** in a consistent and reproducible way

Color space	Advantages	Disadvantages
RGB	Convenient for image acquisition and displaying;	Non-uniform illumination sensitive;
HSV, HSI	Based on human color perception; Robust before non-uniform illumination; The chromaticity is decoupled from the intensity	Differences between colors is not linear Non removable singularities
$L^*a^*b^*$, $L^*u^*v^*$	Efficient in measuring small color difference; The chromaticity is decoupled from the intensity;	Singularity problem as other nonlinear transformations
YUV, YCbCr	Efficient coding color information for TV signal.	Due to the linear transformation, correlation between the component channels exists, although not as high as the RGB space



SC19 – Image Processing

OpenCV / Open and display an image

Acquisition

```
import cv2
```

```
image_rgb = cv2.imread('path/to/image.png')
```

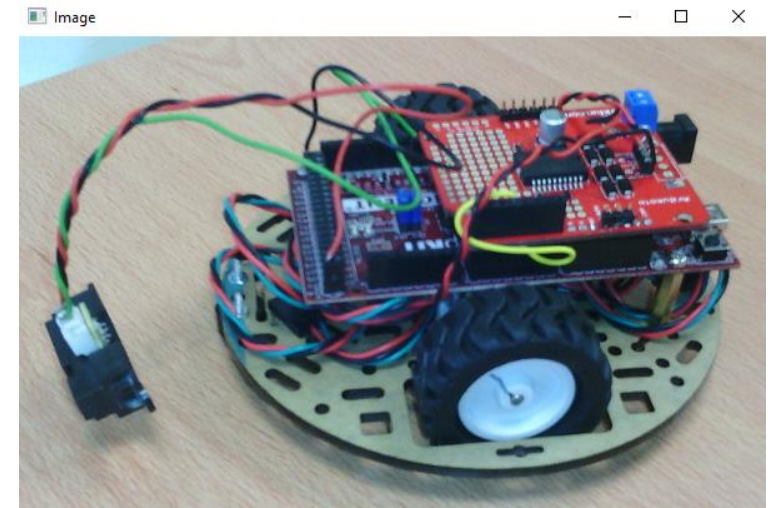
```
image_gray = cv2.imread('path/to/image.png', cv2.IMREAD_GRAYSCALE)
```

```
image = cv2.imread("../_data/robot.pgm")  
print(type(image))
```

```
<class 'numpy.ndarray'>
```

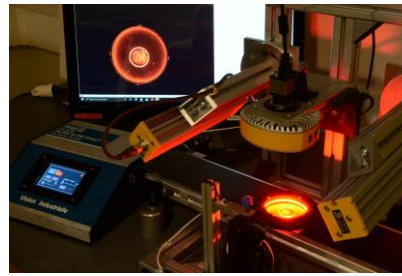
```
print(image.shape)
```

```
(382, 600, 3)
```



```
cv2.imshow('Image ', image_rgb)
```

```
cv2.waitKey(0)
```



SC19 – Image Processing

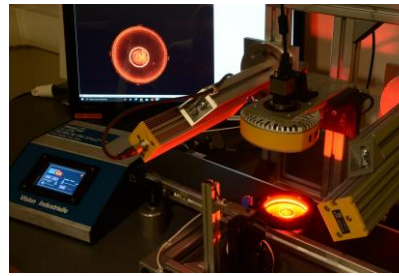
Pre-processing

Acquisition

Pre Processing

Noise Reduction / Filtering
Contrast Enhancement
Normalization

Ensuring clarity and reducing unwanted information
Making features of interest stand out
Standardizing the image scale or intensity



SC19 – Image Processing

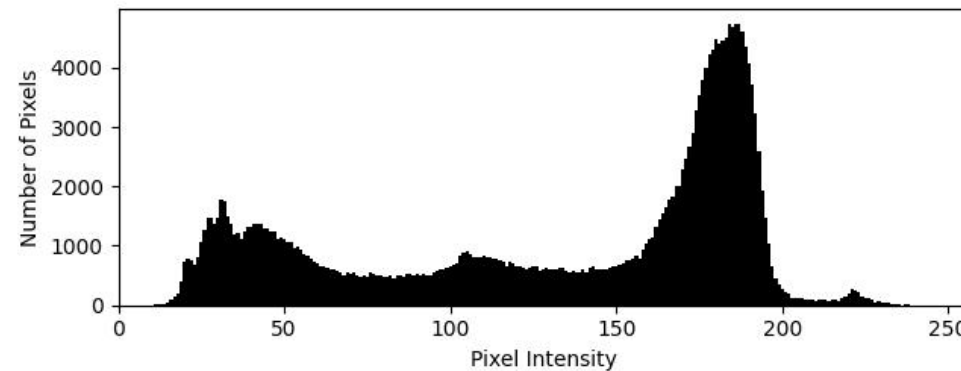
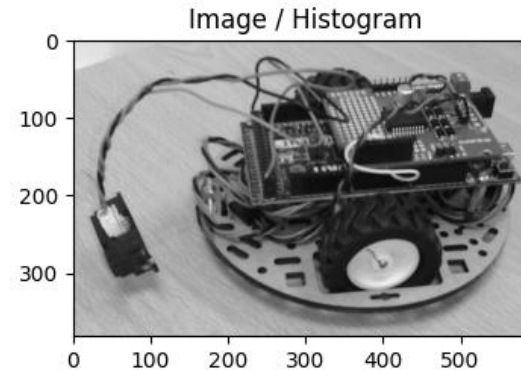
OpenCV / Histogram of an image

Acquisition

Pre Processing

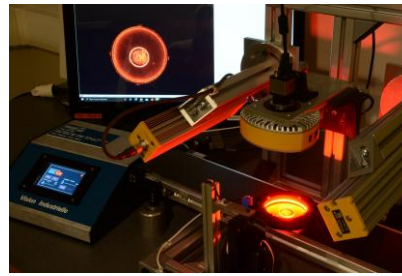
Histogram

Graphical representation that shows the **distribution of pixel intensity values** in an image



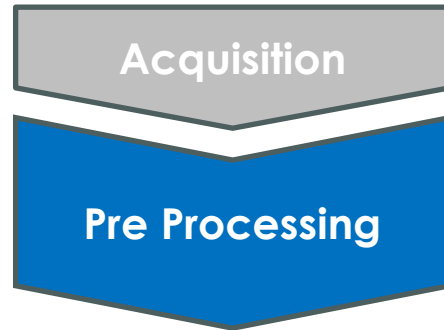
```
cv2.calcHist([image], [chan], Mask, [bins_nb], [min, max])
```

```
histogram = cv2.calcHist([image], [0], None, [256], [0, 256])
```

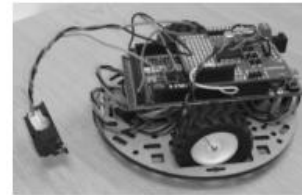


SC19 – Image Processing

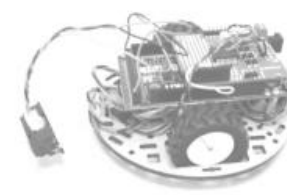
OpenCV / Contrast and Brightness



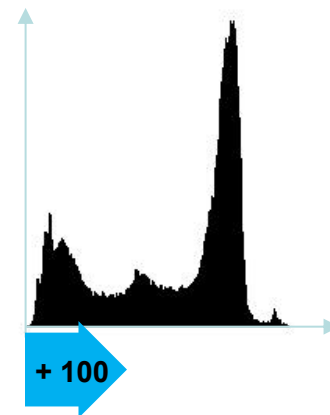
Original Image



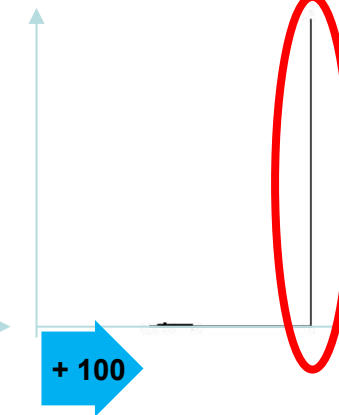
Brighthness Image



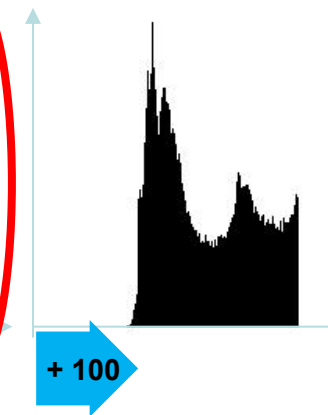
Original Histogram



Brighthness Image



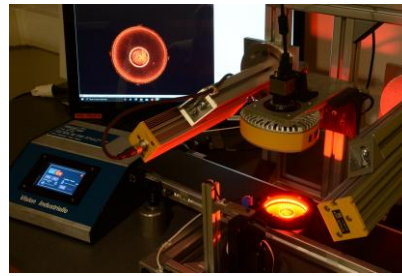
Brighthness Image



```
new_img = cv2.convertScaleAbs(image, beta=100)
```

Acquisition

Pre Processing

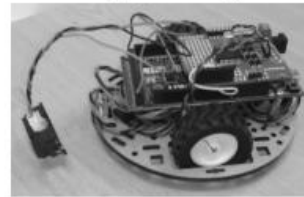


SC19 – Image Processing

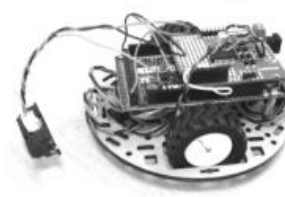
OpenCV / Contrast and Brightness

x 1.5

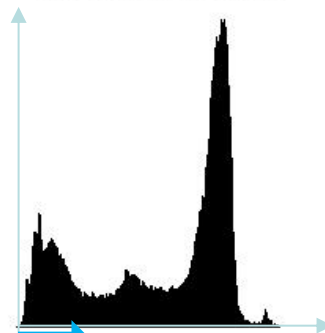
Original Image



Contrast Image

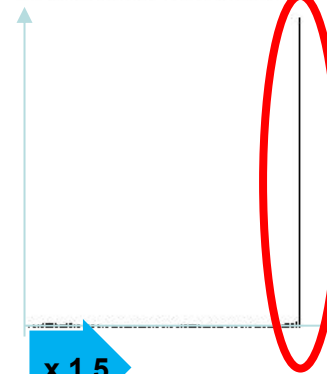


Original Histogram



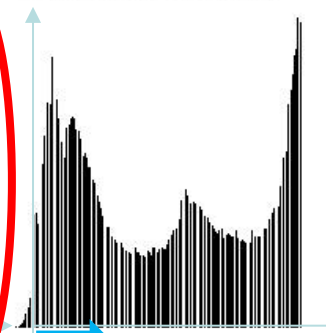
x 1.5

Contrast Histogram



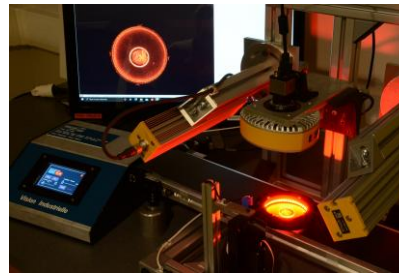
x 1.5

Contrast Histogram



x 1.5

```
new_img = cv2.convertScaleAbs(image, alpha=1.5)
```



SC19 – Image Processing

OpenCV / Convolution

Acquisition

Pre Processing

Convolution (filter)

kernel

-1	0	-2
1	5	1
-2	0	-1

original image

5	8	4	2	3	1	5
9	5	1	8	7	6	2
5	7	1	5	6	8	7
5	8	2	8	4	3	3
5	6	6	7	2	5	1

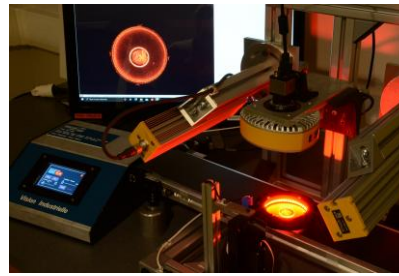
5	8	4	2	3	1	5
9	5	1	8	7	6	2
5	7	1	5	6	8	7
5	8	2	8	4	3	3
5	6	6	7	2	5	1

filtered image

				4		

$$R = -8 + 0 - 12 + 5 + 30 + 8 - 16 + 0 - 3$$

$$R = 4$$



SC19 – Image Processing

OpenCV / Convolution Kernel

Acquisition

Pre Processing

```
kernel = cv2.getStructuringElement(cv2.MORPH_xx, (M,N))
```

Cross Kernel

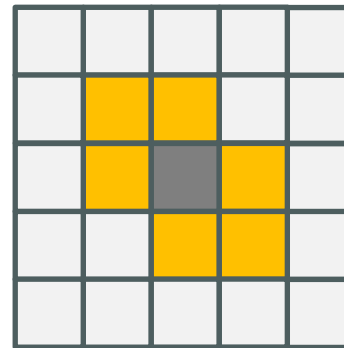
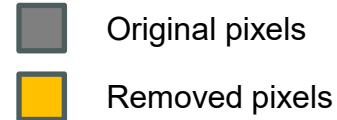
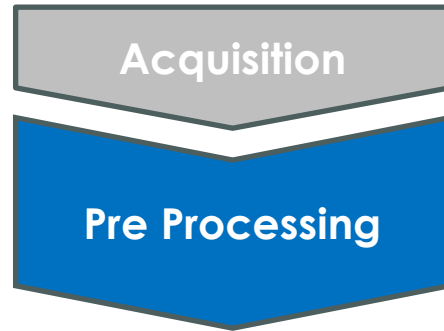
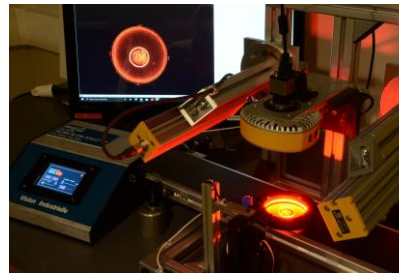
0	0	1	0	0
0	0	1	0	0
1	1	1	1	1
0	0	1	0	0
0	0	1	0	0

cv2.MORPH_CROSS

Rect Kernel

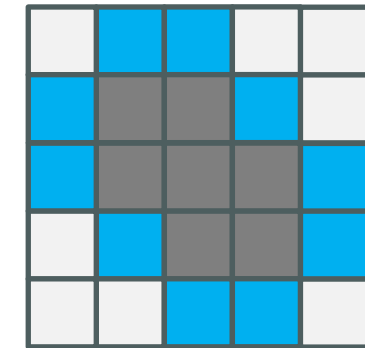
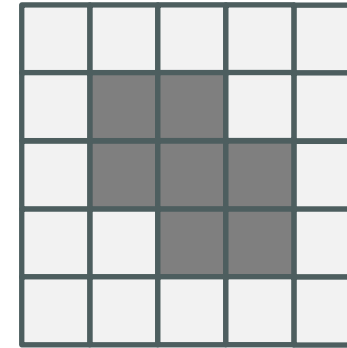
1	1	1	1	1
1	1	1	1	1
1	1	1	1	1
1	1	1	1	1
1	1	1	1	1

cv2.MORPH_RECT



Erosion

Shrinking the foreground by
removing pixels to the
boundaries of objects

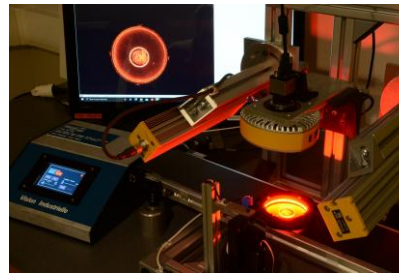


Dilation

Enlarging the foreground by
adding pixels to the boundaries
of objects

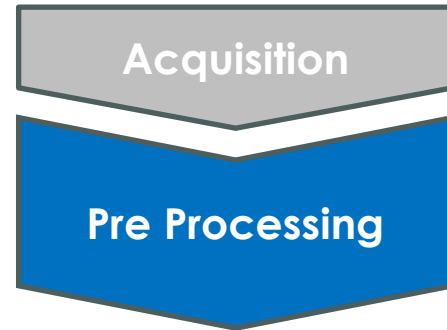
kernel

0	1	0
1	1	1
0	1	0



SC19 – Image Processing

OpenCV / Erosion and Dilation



Eroded Image



Original Image



Dilated Image



kernel

0	1	0
1	1	1
0	1	0

Erosion

Shrinking the foreground by
removing pixels to the
boundaries of objects

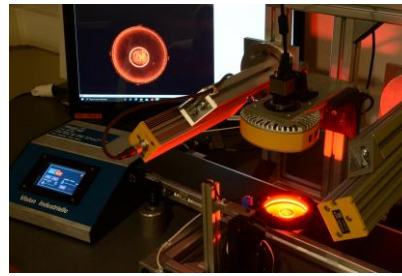
Dilation

Enlarging the foreground by
adding pixels to the boundaries
of objects

```
eroded_image = cv2.erode(image, kernel, iterations=1)
dilated_image = cv2.dilate(image, kernel, iterations=1)
```

Acquisition

Pre Processing



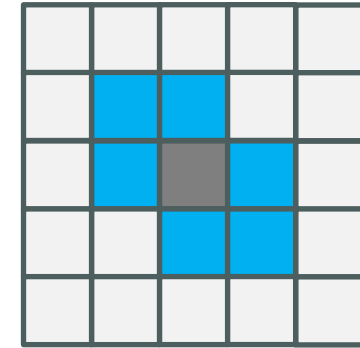
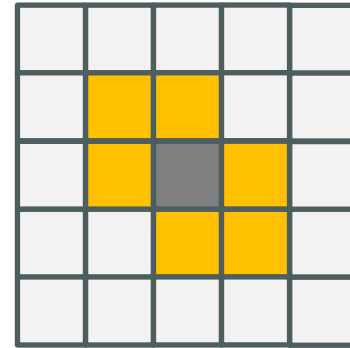
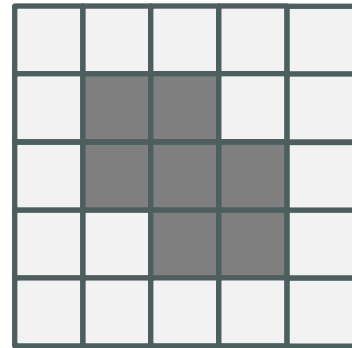
Original pixels



Removed pixels



Added pixels



Opening

Erosion then **Dilation**

Removing small objects

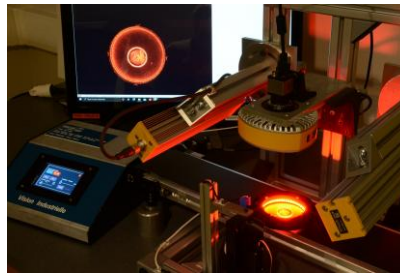
Closing

Dilation then **Erosion**

Filling in small holes

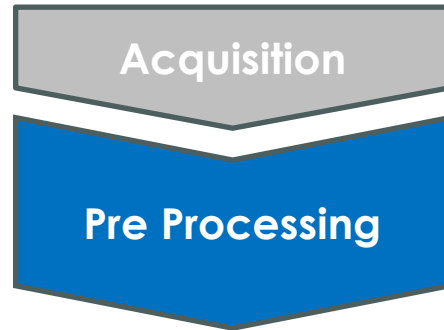
kernel

0	1	0
1	1	1
0	1	0



SC19 – Image Processing

OpenCV / Opening and Closing *morphological transforms*



Opening Image



Original Image



Closing Image



kernel

0	1	0
1	1	1
0	1	0

Opening

Erosion then **Dilation**

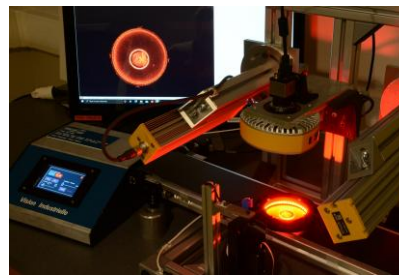
Removing small objects

Closing

Dilation then **Erosion**

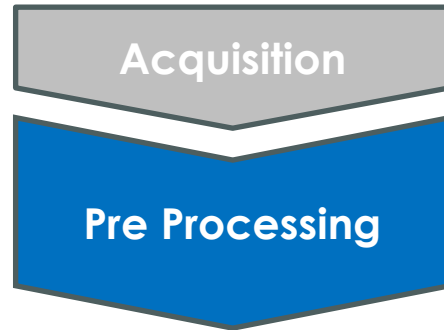
Filling in small holes

```
opening_image = cv2.morphologyEx(image, cv2.MORPH_OPEN, kernel)  
closing_image = cv2.morphologyEx(image, cv2.MORPH_CLOSE, kernel)
```



SC19 – Image Processing

OpenCV / Opening and Closing *morphological transforms*



Opening Image



Original Image



Closing Image



kernel

0	1	0
1	1	1
0	1	0

Opening

Erosion then Dilation

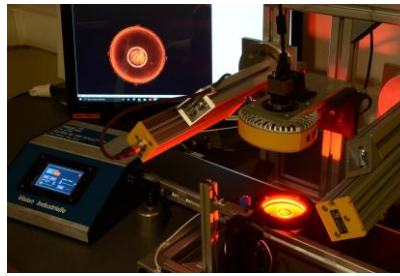
Removing small objects, in
the background

Closing

Dilation then Erosion

Filling in small holes in the
foreground

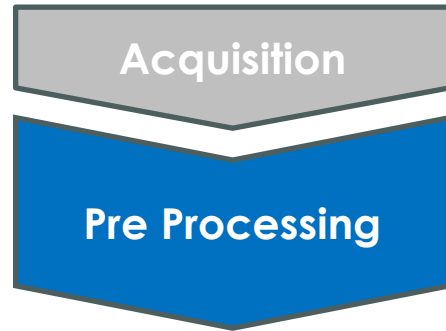
```
opening_image = cv2.morphologyEx(image, cv2.MORPH_OPEN, kernel)
closing_image = cv2.morphologyEx(image, cv2.MORPH_CLOSE, kernel)
```



SC19 – Image Processing

OpenCV / Gradient

morphological transforms



Original Image



Gradient Image



kernel

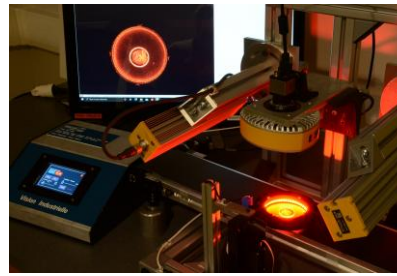
0	1	0
1	1	1
0	1	0

Gradient

Difference between a **dilation** and an **erosion**

Unknown pixels classification : background or foreground ?

```
gradient_image = cv2.morphologyEx(image, cv2.MORPH_GRADIENT, kernel)
```



SC19 – Image Processing

OpenCV / Blur and Mean

morphological transforms

Acquisition

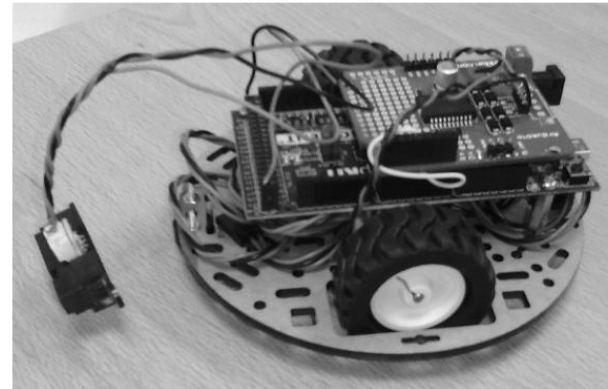
Pre Processing

`kernel_size = (N,M)`

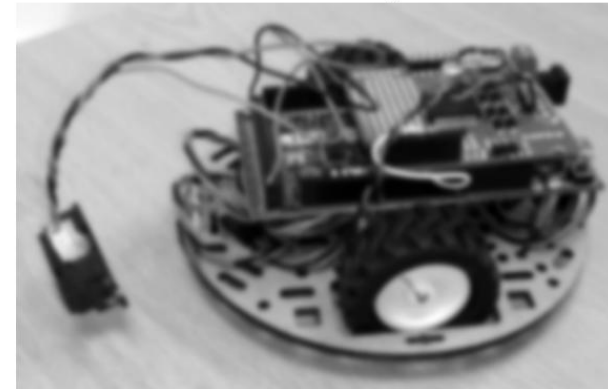
`blurred_image_gauss = cv2.GaussianBlur(image, kernel_size, 0)`

`blurred_image_box = cv2.blur(image, kernel_size)`

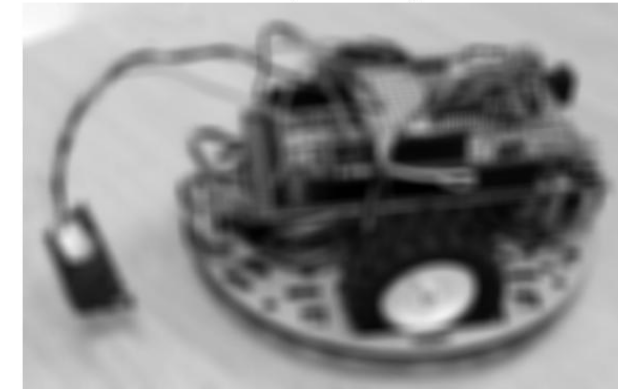
Original Image



Gaussian Blur Image



Median/Box Blur Image



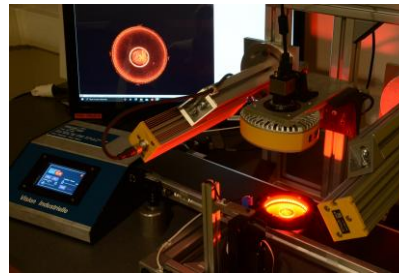
Removing irrelevant details

1	4	7	4	1
4	16	26	16	4
7	26	41	26	7
4	16	26	16	4
1	4	7	4	1

Gaussian Kernel
(x 1/273)

Mean Kernel (x 1/(N*M))

1/9	1/9	1/9
1/9	1/9	1/9
1/9	1/9	1/9



SC19 – Image Processing

OpenCV / Sobel

Acquisition

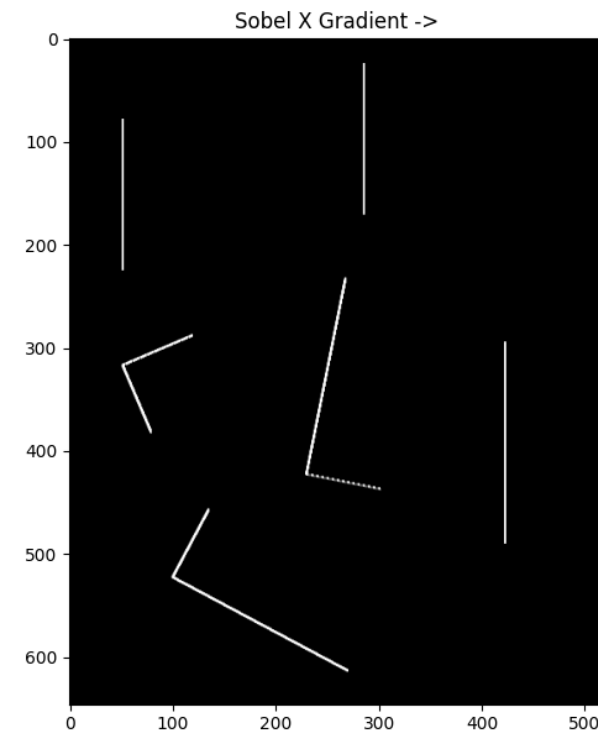
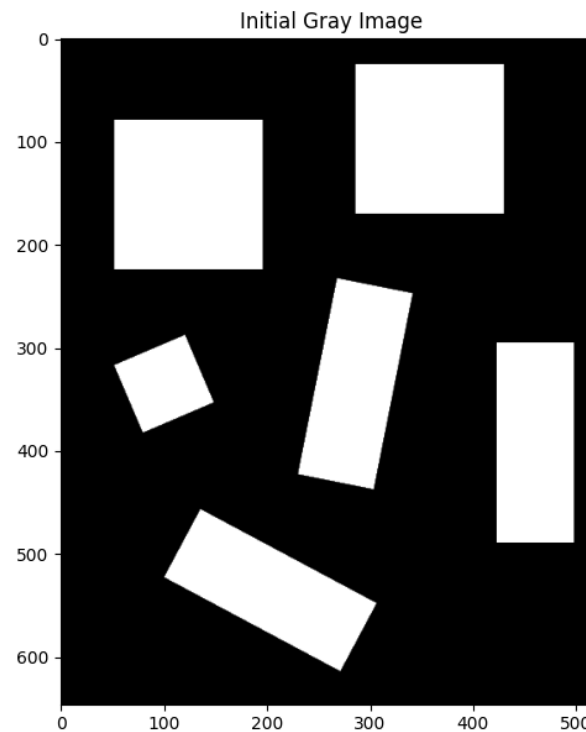
Pre Processing

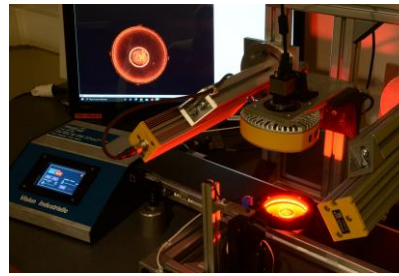
```
sobel_kernel_x1 = np.array([[ -1,  0,  1],
                             [ -2,  0,  2],
                             [ -1,  0,  1]])
```

```
sobelx_1 = cv2.filter2D(image, -1, sobel_kernel_x1)
```

kernel

-1	0	1
-2	0	2
-1	0	1





SC19 – Image Processing

OpenCV / Sobel

Acquisition

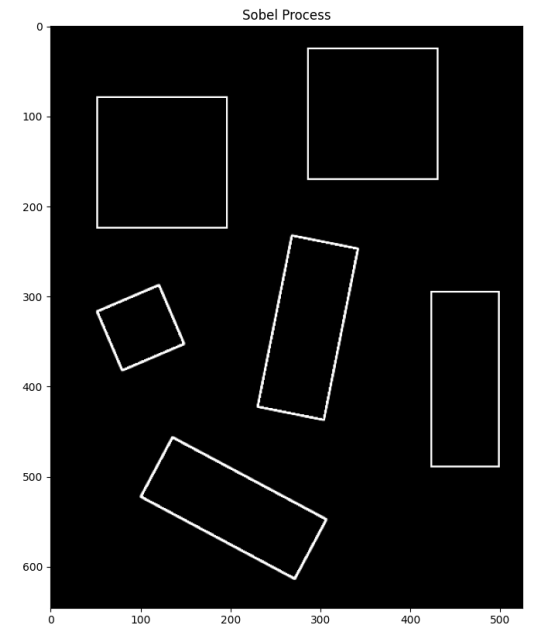
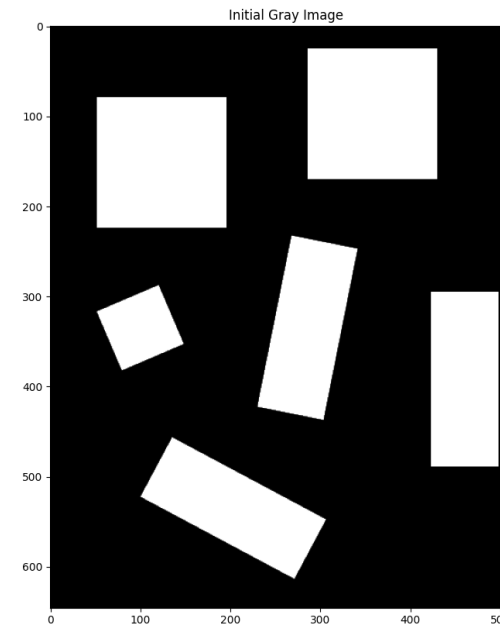
Pre Processing

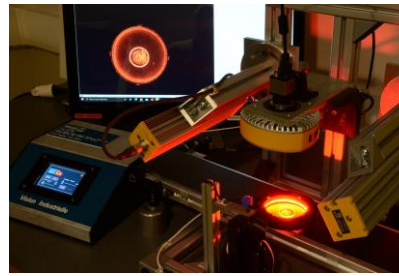
```
sobelx = cv2.Sobel(image_gray, cv2.CV_64F, 1, 0, ksize=3)
sobely = cv2.Sobel(image_gray, cv2.CV_64F, 0, 1, ksize=3)
```

```
magnitude = cv2.magnitude(sobelx, sobely)
magnitude = cv2.convertScaleAbs(magnitude)
```

kernel

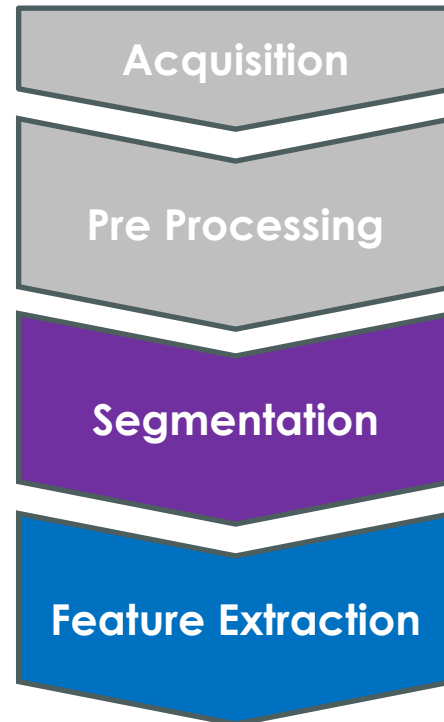
-1	0	1
-2	0	2
-1	0	1





SC19 – Image Processing

Goal of processing an image



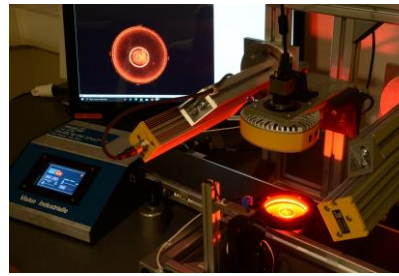
https://docs.opencv.org/4.x/d3/db4/tutorial_py_watershed.html

Thresholding
Edge Detection
Region of Interest Selection

Isolating objects of ROI / Separating product from background
Identifying boundaries and contours
Focusing only on relevant portions of the image

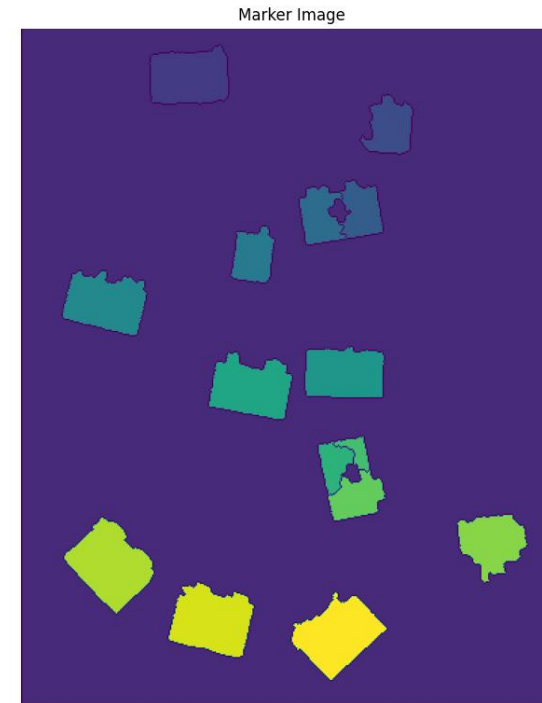
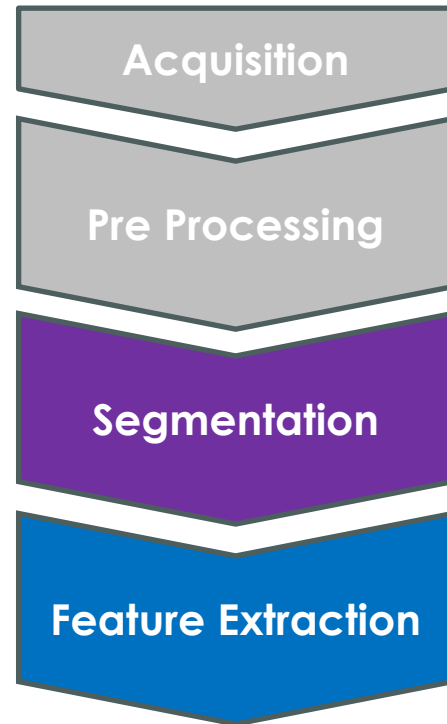
Geometric Features
Texture Analysis
Color Analysis

Extracting measurements (size, shape, position...)
Recognizing patterns, symbols, points of interest

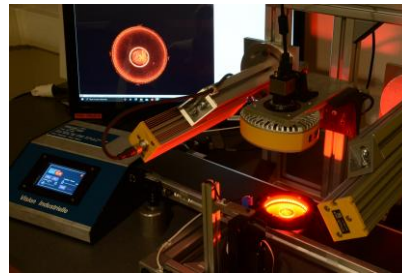


SC19 – Image Processing

Segmentation and Feature extraction

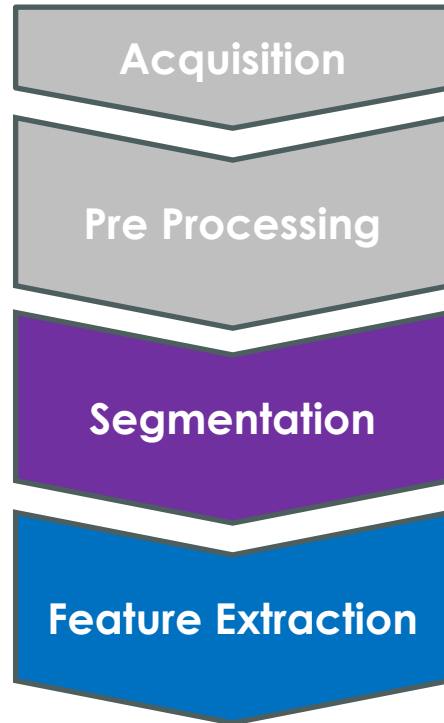


Watershed method



SC19 – Image Processing

Segmentation and Feature extraction



Original RGB Image



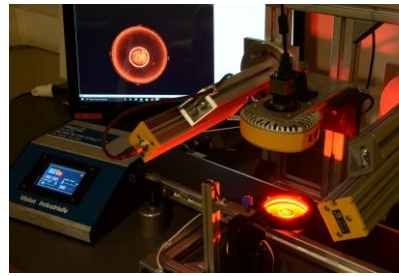
Gray Image



Threshold Image

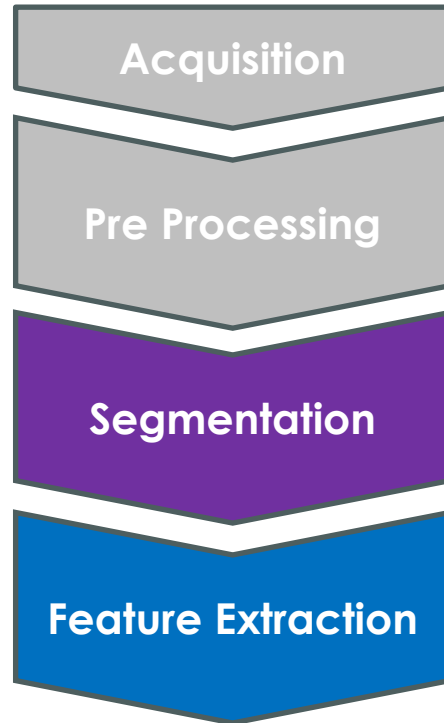


Watershed method / First step - Thresholding



SC19 – Image Processing

Segmentation and Feature extraction



Sure BG Image



Sure FG Image



Watershed method / Second step – Sure BG/FG image

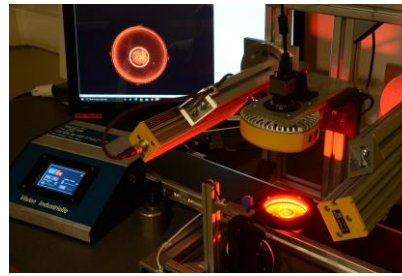
Original Image



Labelling Image

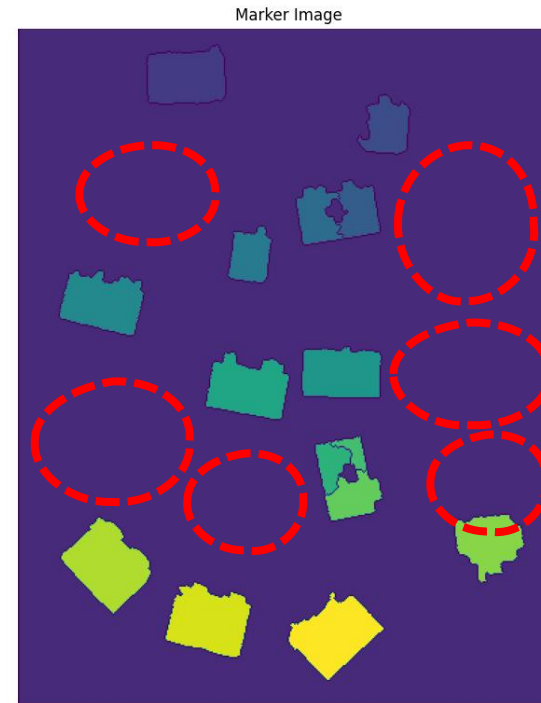
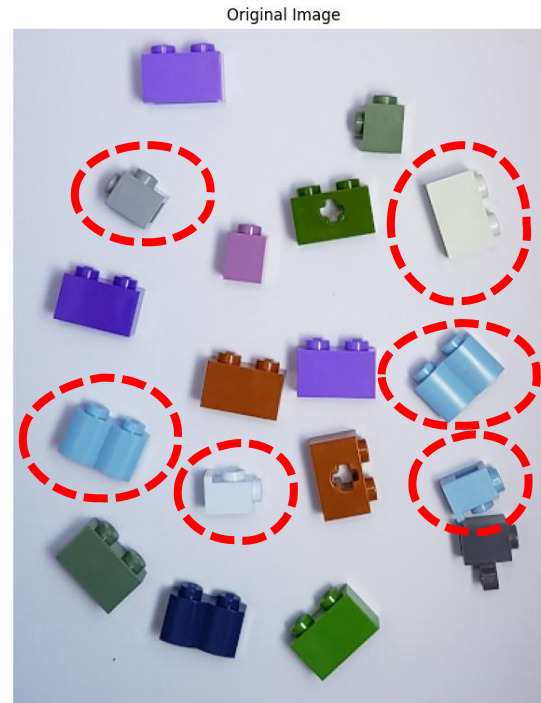
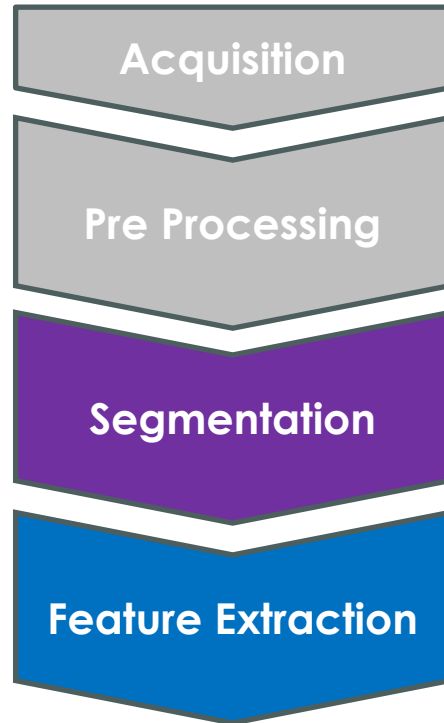


Watershed method / Third step – Labelling

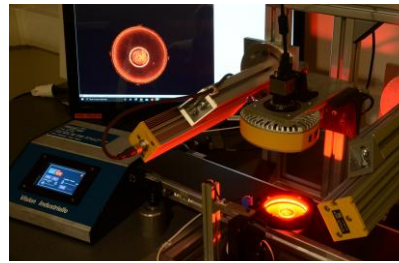


SC19 – Image Processing

Segmentation and Feature extraction



Watershed method



SC19 – Image Processing

Fourier Transform and Filtering

